

# ADMISSIBLE WEAK SOLUTION OF A CONSERVATION LAW BY GLIMM METHOD AND THE POLYGONAL APPROXIMATIONS OF SOLUTIONS

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ABSTRACT. In this paper, we propose an alternative construction based on the Glimm's random choice method [G] and the polygonal approximations of solutions by Dafermos [D] to get an admissible weak solution to the single conservation law.

## 1. INTRODUCTION

We consider the Cauchy problem for a scalar conservation law

$$(1) \quad \begin{cases} u_t + f(u)_x = 0, & (x, t) \in \mathbb{R} \times [0, \infty), \\ u(x, 0) = u_0(x), & x \in \mathbb{R}, \end{cases}$$

where  $f : \mathbb{R} \rightarrow \mathbb{R}$  is locally Lipschitz continuous on  $\mathbb{R}$  and  $u_0(\cdot)$  is bounded, continuous on the left and of locally bounded variation on  $\mathbb{R}$ .

Since  $u_0$  is bounded and  $f$  is locally Lipschitz continuous, we can suppose  $f$  is Lipschitz on  $[-M, M]$ , where  $\|u_0\|_\infty \leq M$ . Without loss of generality, we can assume that  $M$  is a positive integer.

In general no classical solution of (1) exists even if  $f$  and  $u_0$  are smooth. It has been demonstrated that it is possible to establish the existence of weak solutions by many methods, see for example, [B], [B-B], [D], [S] and their references. For more details about the Glimm method see also [G], [L], [H-L] and their references.

The weak solution is not necessarily unique. To attain uniqueness one usually imposes additional restrictions which are motivated by stability arguments or by physical considerations (whenever (1) is studied in connection with a physical model).

In section 2, we will construct a sequence of approximate weak solutions using the Glimm's random choice method [G] and the polygonal approximations of solutions by Dafermos [D]. In section 3, we will use the convergence of the Glimm method to obtain a subsequence convergence and we will show that the limit of this subsequence is an admissible weak solution of (1).

## 2. APPROXIMATION SOLUTION

An admissible weak solution of the Cauchy problem (1) is defined as in [D]:

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**Definition 1.** A locally bounded and measurable function  $u(x, t)$  on  $\mathbb{R} \times [0, \infty)$  is called an admissible weak solution of (1), if for any nondecreasing function  $h(u)$  and any smooth nonnegative function  $\phi(x, t)$  with compact support in  $\mathbb{R} \times [0, \infty)$ ,

$$(2) \quad \int_0^\infty \int_{-\infty}^\infty (I(u)\phi_t + F(u)\phi_x) dx dt + \int_{-\infty}^\infty I(u_0(x))\phi(x, 0) dx \geq 0,$$

where

$$I(u) \equiv \int_{-M}^u h(\xi) d\xi$$

and

$$F(u) \equiv \int_{-M}^u h(\xi) df(\xi).$$

**Remark 1.** An application of (2) for  $h(u) = 1$  and  $h(u) = -1$  yields

$$(3) \quad \int_0^\infty \int_{-\infty}^\infty (u\phi_t + f(u)\phi_x) dx dt + \int_{-\infty}^\infty u_0(x)\phi(x, 0) dx = 0.$$

which is the standard condition satisfied by any weak solution of (1).

**Remark 2.** If  $u(x, t)$  is defined on  $\mathbb{R} \times [0, T)$  and (2) is satisfied for every nonnegative  $\phi(x, t)$  with compact support in  $\mathbb{R} \times [0, T)$ , then  $u(x, t)$  is called a local admissible weak solution of (1) on  $\mathbb{R} \times [0, T)$ , according to [D].

Initially, we assume that  $u_0$  is of bounded variation on  $\mathbb{R}$ .

Fix an integer  $k \geq 1$ . Let  $P = \{x_0 = -M < x_1 < \dots < x_s = M\}$  be the partition of  $[-M, M]$  such that  $x_j - x_{j-1} = 2^{-k}$ ,  $j = 1, 2, \dots, s$ , ( $s = 2^{k+1}M$ ). Let  $f_k$  be the piecewise linear function which coincides with  $f$  at all points  $x_j \in P$ , i.e.

$$(4) \quad f_k(r) = \frac{r - x_{j-1}}{2^{-k}} f(x_j) + \frac{x_j - r}{2^{-k}} f(x_{j-1}),$$

where  $r \in [x_{j-1}, x_j]$ ,  $j = 1, 2, \dots, s$ .

Let  $K$  be the Lipschitz constant such that

$$(5) \quad |f(w) - f(z)| \leq K|w - z|, \quad \forall w, z \in [-M, M],$$

hence

$$(6) \quad |f_k(w) - f_k(z)| \leq K|w - z|, \quad \forall w, z \in [-M, M],$$

$\forall k \in \mathbb{N}$ . Without loss of generality, we can assume that  $K \geq 1$ .

For each fixed  $k \geq 1$ , we consider the conservation law

$$(7) \quad u_t + f_k(u)_x = 0, \quad (x, t) \in \mathbb{R} \times [0, \infty),$$

First, we choose mesh lengths  $\Delta x_k$  and  $\Delta t_k$  such that the stability condition  $\frac{\Delta x_k}{\Delta t_k} = C > K$  holds, where  $C$  is constant and independent of  $k$ . We assume that  $\Delta x_k = 2^{-k}$ . Let

$$Y \equiv \{(m, n) \in \mathbb{Z}^2 : m + n \equiv 0 \pmod{2}, n \geq 0\}$$

and

$$\Phi \equiv \Pi_{(m,n) \in Y} \{[(m-1)\Delta x_k, (m+1)\Delta x_k] \times \{n\Delta t_k\}\}.$$

We choose a point  $(m\Delta x_k + \theta_n \Delta x_k, n\Delta t_k)_{(m,n) \in Y} \in \Phi$  where  $\theta_n$  is randomly chosen in  $[-1, 1]$ . As in [S], there is an isomorphism,  $\Phi \approx \prod [0, 1]$ , of  $\Phi$  with a countable product of copies of the unit interval, so we can consider the random points  $\theta$  being defined in a fixed probability space  $\Phi$ , independent of  $\Delta x_k$ .

Now, we consider the initial data

$$(8) \quad u_0^{(k,m)}(x, 0) = \begin{cases} u_0((m-1 + \theta_0)\Delta x_k), & (m-1)\Delta x_k < x \leq m\Delta x_k \\ u_0((m+1 + \theta_0)\Delta x_k), & m\Delta x_k < x \leq (m+1)\Delta x_k, \end{cases}$$

where  $m \in \mathbb{Z}$ , such that  $m$  is even.

In [D], we have

**Lemma 1.** *If  $f$  is piecewise linear, satisfies (5), and*

$$\bar{u}_0(x) \equiv \begin{cases} u_l, & x \in (-\infty, y], \\ u_r, & x \in (y, \infty), \end{cases}$$

where  $u_l$  and  $u_r$  are constants in  $[-M, M]$  and  $y$  is constant in  $\mathbb{R}$ , then there exists an admissible weak solution  $u$  of (1), continuous on the left, that consists of a finite number of constant states separated by shock waves centered at  $y$ . Moreover,  $TV(u(\cdot, t)) \leq |u_r - u_l|$ ,  $\forall t \in [0, \infty)$ , and  $|u(x, t)| \leq \|\bar{u}_0\|_\infty$ ,  $\forall (x, t) \in \mathbb{R} \times [0, \infty)$ .

**Remark 3.** *The values intermediaries that the admissible weak solution assume are always vertices of the polygonal  $f_k$ .*

**Remark 4.** *The admissible weak solution is always increasing or decreasing. Moreover, each shock wave  $x = \tilde{x}(t)$ ,  $t \in (0, \Delta t_k)$ , is a straight line with slope*

$$\frac{d\tilde{x}}{dt} = \frac{f_k(u^+) - f_k(u^-)}{u^+ - u^-},$$

and for any  $u$  between  $u^-$  and  $u^+$ ,

$$\frac{f_k(u^+) - f_k(u)}{u^+ - u} \leq \frac{f_k(u^+) - f_k(u^-)}{u^+ - u^-},$$

where  $u^+ = \lim_{x \rightarrow \tilde{x}(t)^+} u(x, t)$  and  $u^- = \lim_{x \rightarrow \tilde{x}(t)^-} u(x, t)$ .

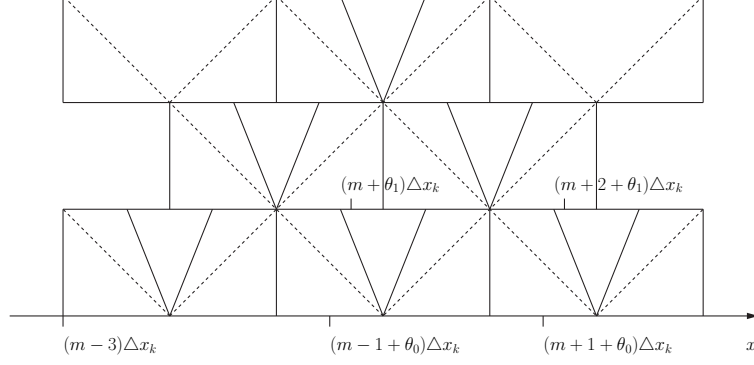
For each fixed  $k \in \mathbb{N}$  and for each fixed  $m \in \mathbb{Z}$ , such that  $m$  is even, the Riemann problem

$$v_t + f_k(v)_x = 0, \quad (x, t) \in \mathbb{R} \times [0, \infty),$$

with initial data

$$v(x, 0) = \begin{cases} u_0((m-1 + \theta_0)\Delta x_k), & x \in (-\infty, m\Delta x_k] \\ u_0((m+1 + \theta_0)\Delta x_k), & x \in (m\Delta x_k, \infty), \end{cases}$$

is solved by Lemma 1. Let  $v_{k,m,0}$  be the admissible weak solution this problem, given by Lemma 1.

FIGURE 1. Model to construct of the function  $u_{k,n}$ .

Now, for each fixed  $k \in \mathbb{N}$ , we define

$$u_{k,1}(x, t) \equiv v_{k,m,0}(x, t), \quad (m-1)\Delta x_k \leq x \leq (m+1)\Delta x_k, \quad 0 \leq t < \Delta t_k,$$

where  $m \in \mathbb{Z}$  is even.

In view of our stability condition  $\frac{\Delta x_k}{\Delta t_k} = C > K$ , the waves don't interact with each other across the lines  $x = (m-1)\Delta x_k$ .

Thus  $u_{k,1}$  is a step function defined in the strip  $0 \leq t < \Delta t_k$ , constant across the lines  $x = (m-1)\Delta x_k$ ,  $\forall m \in \mathbb{Z}$  even, and continuous on the left. According to Remark 2,  $u_{k,1}$  is a local admissible weak solution of (7) and (8),  $\forall m \in \mathbb{Z}$  even.

We also have that  $TV(u_{k,1}(\cdot, t)) \leq TV(u_0(\cdot))$ ,  $\forall t \in [0, \Delta t_k)$ , and  $|u_{k,1}(x, t)| \leq \|u_0\|_\infty$ ,  $\forall (x, t) \in \mathbb{R} \times [0, \Delta t_k)$ .

Inductively, we assume that  $u_{k,n}$  had been defined in the strip  $\mathbb{R} \times [(n-1)\Delta t_k, n\Delta t_k)$ . (Fig. 1).

In analogous way, we define  $u_{k,n+1}$  to solve the Riemann problem

$$v_t + f_k(v)_x = 0, \quad (x, t) \in \mathbb{R} \times [n\Delta t_k, \infty),$$

with initial data

$$v(x, n\Delta t_k) = \begin{cases} u_{k,n}((m-1+\theta_n)\Delta x_k, n\Delta t_k^-), & x \in (-\infty, m\Delta x_k], \\ u_{k,n}((m+1+\theta_n)\Delta x_k, n\Delta t_k^-), & x \in (m\Delta x_k, \infty), \end{cases}$$

where  $(m, n) \in Y$  and  $\Delta t_k^- = \lim_{t \rightarrow \Delta t_k^-} t$ . Let  $v_{k,m,n}$  the admissible weak solution this problem, given by Lemma (1). (See fig (1)).

We define  $u_{k,n+1} \equiv v_{k,m,n}$  in the strip  $\mathbb{R} \times [n\Delta t_k, (n+1)\Delta t_k)$ . Hence, we have that  $TV(u_{k,n+1}(\cdot, t)) \leq TV(u_0(\cdot))$ ,  $\forall t \in [n\Delta t_k, (n+1)\Delta t_k)$ , and  $|u_{k,n+1}(x, t)| \leq \|u_0\|_\infty$ ,  $\forall (x, t) \in \mathbb{R} \times [n\Delta t_k, (n+1)\Delta t_k)$ ,  $\forall n = 0, 1, 2, \dots$

In particular,  $u_{k,n+1}$  is piecewise constant, continuous on the left, with jumps occurring along of straing lines in the strip  $\mathbb{R} \times [n\Delta t_k, (n+1)\Delta t_k)$ , for each fixed  $n \in \mathbb{N}$ .

For each fixed  $k \in \mathbb{N}$  and for each fixed  $\theta \in \Phi$ , we define

$$u_{(\theta,k)}(x,t) \equiv u_{(\theta,\Delta x_k)}(x,t) \equiv u_{k,n}(x,t), \quad (x,t) \in \mathbb{R} \times [(n-1)\Delta t_k, n\Delta t_k),$$

$n \in \mathbb{N}$ .

**Remark 5.** Since  $\frac{\Delta x_k}{\Delta t_k} = C > K$ , the restriction of  $u_{(\theta,k)}(\cdot, t)$  on any interval  $[x_1, x_2]$ , is solely determined by the restriction of  $u_0(\cdot)$  on the interval  $[x_1 - (1+Kt), x_2 + (1+Kt)]$  (finite domain of dependence) and

$$TV_{[x_1, x_2]}(u_{(\theta,k)}(\cdot, t)) \leq TV_{[x_1 - (1+Kt), x_2 + (1+Kt)]}(u_0(\cdot)).$$

**Lemma 2.** For each fixed  $k \in \mathbb{N}$ , for each nondecreasing function  $h(u)$  and each nonnegative function  $\phi \in C_0^1(t \geq 0)$ , we have that, in each strip  $\mathbb{R} \times (l\Delta t_k, (l+1)\Delta t_k)$ ,

$$\begin{aligned} & \int_{l\Delta t}^{(l+1)\Delta t} \int_{-\infty}^{\infty} (I(u_{(\theta,k)})\phi_t + F_k(u_{(\theta,k)})\phi_x) dx dt \\ & \quad + \int_{-\infty}^{\infty} I(u_{(\theta,k)}(x, l\Delta t_k^+))\phi(x, l\Delta t_k) dx \\ & \quad - \int_{-\infty}^{\infty} I(u_{(\theta,k)}(x, (l+1)\Delta t_k^-))\phi(x, (l+1)\Delta t_k) dx \geq 0, \end{aligned}$$

where

$$F_k(u) \equiv \int_{-M}^u h(\xi) df_k(\xi).$$

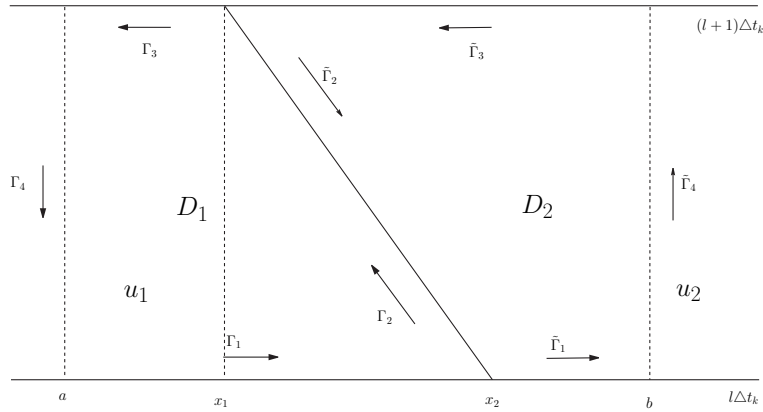


FIGURE 2. Model of local admissible weak solution in the strip  $\mathbb{R} \times (l\Delta t_k, (l+1)\Delta t_k)$ .

*Proof.* Indeed, without loss of generality, we assume that in the strip  $\mathbb{R} \times (l\Delta t_k, (l+1)\Delta t_k)$ , there exists only a discontinuity  $\tilde{x}(t)$ , with slope  $\alpha = \frac{f_k(u_2) - f_k(u_1)}{u_2 - u_1}$ , according to [D], connecting the states  $u_1$  and  $u_2$ , (Fig. 2).

In this case, we observe that the line of discontinuity  $\tilde{x}(t)$  subdivides the strip  $\mathbb{R} \times (l\Delta t_k, (l+1)\Delta t_k)$  into two disjoint regions  $D_1$  and  $D_2$ .

We assume that the compact support of  $\phi$  is in  $[a, b] \times [0, \infty)$ . We notice that  $\phi(a, t) = \phi(b, t) = 0, \forall t \in [0, \infty)$ . The oriented boundary of  $D_1$  is parametrized by  $\Gamma_1(s) = (s, l\Delta t_k)$  where  $a \leq s \leq x_2$ ,  $\Gamma_2(s) = (\tilde{x}(s), s)$  where  $l\Delta t_k \leq s \leq (l+1)\Delta t_k$  and  $\Gamma_3(s) = ((x_1 + a) - s, (l+1)\Delta t_k)$  where  $a \leq s \leq x_1$ . In analogous way, the oriented boundary of  $D_2$  is parametrized by  $\tilde{\Gamma}_1(s) = (s, l\Delta t_k)$  where  $x_2 \leq s \leq b$ ,  $\tilde{\Gamma}_2(s) = (\tilde{x}((2l+1)\Delta t_k - s), (2l+1)\Delta t_k - s)$  where  $l\Delta t_k \leq s \leq (l+1)\Delta t_k$  and  $\tilde{\Gamma}_3(s) = ((b + x_1) - s, (l+1)\Delta t_k)$  where  $x_1 \leq s \leq b$ .

Integrating, we have

$$\begin{aligned} & \int_{l\Delta t_k}^{(l+1)\Delta t_k} \int_{-\infty}^{\infty} (I(u_{(\theta,k)})\phi_t + F_k(u_{(\theta,k)})\phi_x) dx dt = \\ & \int \int_{D_1} (I(u_1)\phi_t + F_k(u_1)\phi_x) dx dt + \int \int_{D_2} (I(u_2)\phi_t + F_k(u_2)\phi_x) dx dt. \end{aligned}$$

By Green's theorem, we have

$$\begin{aligned} & \int \int_{D_1} (I(u_1)\phi_t + F_k(u_1)\phi_x) dx dt = \\ & - \int_a^{x_2} I(u_1)\phi(x, l\Delta t_k^+) dx + \int_a^{x_1} I(u_1)\phi(x, (l+1)\Delta t_k^-) dx \\ & + \int_{l\Delta t_k}^{(l+1)\Delta t_k} [-\alpha I(u_1) + F_k(u_1)]\phi(\tilde{x}(s), s) ds \end{aligned}$$

and

$$\begin{aligned} & \int \int_{D_2} (I(u_2)\phi_t + F_k(u_2)\phi_x) dx dt = \\ & - \int_{x_2}^b I(u_2)\phi(x, l\Delta t_k^+) dx + \int_{x_1}^b I(u_2)\phi(x, (l+1)\Delta t_k^-) dx \\ & + \int_{l\Delta t_k}^{(l+1)\Delta t_k} [\alpha I(u_2) - F_k(u_2)]\phi(\tilde{x}(s), s) ds. \end{aligned}$$

Therefore,

$$\begin{aligned}
 & \int_{l\Delta t_k}^{(l+1)\Delta t_k} \int_{-\infty}^{\infty} (I(u_{(\theta,k)})\phi_t + F_k(u_{(\theta,k)})\phi_x) dx dt = \\
 & \quad - \int_a^b I(u_{(\theta,k)}(x, l\Delta t_k^+))\phi(x, l\Delta t_k) dx \\
 & \quad + \int_a^b I(u_{(\theta,k)}(x, (l+1)\Delta t_k^-))\phi(x, (l+1)\Delta t_k) dx \\
 & \quad + \int_{l\Delta t_k}^{(l+1)\Delta t_k} [\alpha(I(u_2) - I(u_1)) + (F_k(u_1) - F_k(u_2))]\phi(\tilde{x}(s), s) dt.
 \end{aligned}$$

Since  $\alpha = \frac{f_k(u_2) - f_k(u_1)}{u_2 - u_1}$ , according to [D], so by Lemma 6.1 of [G-R] we have that

$$\frac{f_k(u_2) - f_k(u_1)}{u_2 - u_1} (I(u_2) - I(u_1)) + (F_k(u_1) - F_k(u_2)) \geq 0.$$

It follows that

$$\begin{aligned}
 & \int_{l\Delta t_k}^{(l+1)\Delta t_k} \int_{-\infty}^{\infty} (I(u_{(\theta,k)})\phi_t + F_k(u_{(\theta,k)})\phi_x) dx dt \\
 & \quad + \int_{-\infty}^{\infty} I(u_{(\theta,k)}(x, l\Delta t_k^+))\phi(x, l\Delta t_k) dx \\
 & \quad - \int_{-\infty}^{\infty} I(u_{(\theta,k)}(x, (l+1)\Delta t_k^-))\phi(x, (l+1)\Delta t_k) dx \geq 0.
 \end{aligned}$$

□

### 3. CONVERGENCE

By constructing, the sequence of functions  $(u_{(\theta,k)})$  satisfies

$$(9) \quad \|u_{(\theta,k)}(\cdot, \cdot)\|_{\infty} \leq \|u_0\|_{\infty} = M_1,$$

$$(10) \quad TV(u_{(\theta,k)}(\cdot, t)) \leq TV(u_0(\cdot)) = M_2,$$

where  $M_1$  is independent of  $\theta$  and  $k$ , and  $M_2$  is independent of  $\theta$ ,  $k$  and  $t$ .

**Lemma 3.** *Let  $t_1, t_2 \geq 0$ , then*

$$(11) \quad \int_{-\infty}^{\infty} |u_{(\theta,k)}(x, t_1) - u_{(\theta,k)}(x, t_2)| dx \leq M_3[|t_1 - t_2| + \Delta t_k].$$

where  $M_3$  is independent of  $\theta$ ,  $k$ ,  $t_1$  and  $t_2$ .

The proof is analogous as the corresponding result in [S], Corollary 19.8. Since  $(u_{(\theta,k)})$  satisfies (9), (10) and (11), we have that

**Theorem 2.** *There is a subsequence  $(u_{(\theta,k_j)}) \subset (u_{(\theta,k)})$  convergent in  $L^1_{loc}(\mathbb{R} \times [0, \infty); \mathbb{R})$  to a function  $u_{\theta}$ , for each fixed  $\theta \in \Phi$ .*

The proof is carried out in the same way as [S].

Now, we must use the Glimm method to show that the limit function is an admissible weak solution of (1).

Let  $\theta \in \Phi$ , given any nondecreasing function  $h(u)$  and any nonnegative function  $\phi \in C_0^1(t \geq 0)$ , we define a functional  $\mathcal{L}_\phi$  by (12)

$$\mathcal{L}_\phi(I(u), F(u)) \equiv \int_0^\infty \int_{-\infty}^\infty (I(u)\phi_t + F(u)\phi_x) dx dt + \int_{-\infty}^\infty I(u_0(x))\phi(x, 0) dx.$$

Our goal is to produce a  $u_\theta$  for which  $\mathcal{L}_\phi(I(u_\theta), F(u_\theta)) \geq 0$  for each nondecreasing function  $h(u)$  and each nonnegative function  $\phi \in C_0^1(t \geq 0)$ .

For each fixed  $k \in \mathbb{N}$ , for each nondecreasing function  $h(u)$  and each nonnegative function  $\phi \in C_0^1(t \geq 0)$ , the function  $u_{(\theta, k)}$  satisfies

$$\begin{aligned} & \int_{l\Delta t_k}^{(l+1)\Delta t_k} \int_{-\infty}^\infty (I(u_{(\theta, k)})\phi_t + F_k(u_{(\theta, k)})\phi_x) dx dt \\ & \quad + \int_{-\infty}^\infty I(u_{(\theta, k)}(x, l\Delta t_k^+))\phi(x, l\Delta t_k) dx \\ & \quad - \int_{-\infty}^\infty I(u_{(\theta, k)}(x, (l+1)\Delta t_k^-))\phi(x, (l+1)\Delta t_k) dx \geq 0. \end{aligned}$$

in the strip  $l\Delta t_k \leq t < (l+1)\Delta t_k$ , for each  $l \in \mathbb{N}$ , according to Lemma 2.

If we sum this over  $l$  we get

$$\begin{aligned} & \int_0^\infty \int_{-\infty}^\infty (I(u_{(\theta, k)})\phi_t + F_k(u_{(\theta, k)})\phi_x) dx dt + \int_{-\infty}^\infty I(u_{(\theta, k)}(x, 0))\phi(x, 0) dx \\ & \quad + \sum_{l=1}^\infty \int_{-\infty}^\infty [I(u_{(\theta, k)})](x, l\Delta t_k)\phi(x, l\Delta t_k) dx \geq 0, \end{aligned}$$

where  $[I(u_{(\theta, k)})](x, l\Delta t_k) \equiv I(u_{(\theta, k)}(x, l\Delta t_k^+)) - I(u_{(\theta, k)}(x, l\Delta t_k^-))$ .

Now, we have that

**Lemma 4.** *For each nondecreasing function  $h(u)$ , and each nonnegative function  $\phi \in C_0^1(t \geq 0)$ , we have*

$$\int \int_{t \geq 0} (I(u_{(\theta, k)})\phi_t + F_k(u_{(\theta, k)})\phi_x) dx dt \rightarrow \int \int_{t \geq 0} (I(u_\theta)\phi_t + F(u_\theta)\phi_x) dx dt,$$

when  $k \rightarrow \infty$ .

*Proof.* Indeed, following [D], let  $k \in \mathbb{N}$  be fixed, if  $u \in [-M, M]$ , then there exist  $p \in P$  such that  $|u - p| \leq 2^{-k}$ , so

$$(13) \quad |f(u) - f_k(u)| \leq |f(u) - f_k(p)| + |f_k(p) - f_k(u)| \leq 2K|u - p| \leq \frac{K}{2^{k-1}}.$$

We notice that

$$(14) \quad |F_k(u_{(\theta, k)}) - F(u_\theta)| \leq |F_k(u_{(\theta, k)}) - F_k(u_\theta)| + |F_k(u_\theta) - F(u_\theta)|.$$



We set  $H \equiv \max\{|h(-M)|, |h(M)|\}$ , so

$$(15) \quad |I(u_{(\theta,k)}) - I(u_\theta)| \leq \left| \int_{u_\theta}^{u_{(\theta,k)}} h(\xi) d\xi \right| \leq H |u_{(\theta,k)} - u_\theta|,$$

$$\begin{aligned} |F(u_\theta) - F_k(u_\theta)| &= \left| \int_{-M}^{u_\theta} h(\xi) df(\xi) - \int_{-M}^{u_\theta} h(\xi) df_k(\xi) \right| \\ &\leq \left| \int_{-M}^{u_\theta} h(\xi) d(f(\xi) - f_k(\xi)) \right| \\ &\leq |h(u)(f(u_\theta) - f_k(u_\theta))| + \left| \int_{-M}^{u_\theta} (f(\xi) - f_k(\xi)) dh(\xi) \right| \\ &\leq \frac{K}{2^{k-1}} (H + 2H) \\ (16) \quad &\leq \frac{3HK}{2^{k-1}}, \end{aligned}$$

$$(17) \quad |F_k(u_{(\theta,k)}) - F_k(u_\theta)| = \left| \int_{u_\theta}^{u_{(\theta,k)}} h(\xi) df_k(\xi) \right| \leq HK |u_{(\theta,k)} - u_\theta|.$$

Let  $B \subset \mathbb{R} \times [0, \infty)$  be a subset compact. From (13)-(17) we have

$$\int \int_B |I(u_{(\theta,k)}) - I(u_\theta)| dx dt \leq H \int \int_B |u_{(\theta,k)} - u_\theta| dx dt \rightarrow 0,$$

when  $k \rightarrow \infty$ , and

$$\begin{aligned} \int \int_B |F_k(u_{(\theta,k)}) - F(u_\theta)| dx dt &\leq \frac{K}{2^{k-1}} C \\ &\quad + HK \int \int_B |u_{(\theta,k)} - u_\theta| dx dt \rightarrow 0, \end{aligned}$$

when  $k \rightarrow \infty$ , where  $C$  is a constant that only dependent of  $B$  and of  $h$ . Since  $u_{(\theta,k)} \rightarrow u_\theta$  in  $L^1_{loc}(\mathbb{R} \times [0, \infty); \mathbb{R})$ .  $\square$

Thus our existence theorem will be proved if we can show the next Lemma.

**Lemma 5.** *Let  $\theta \in \Phi$ . Then  $u_\theta = \lim_{k \rightarrow \infty} u_{(\theta,k)}$  is an admissssible weak solution of (1) provided that the following two conditions hold:*

$$(18) \quad I(u_{(\theta,k)}(\cdot, 0)) \rightarrow I(u_0(\cdot)),$$

and

$$(19) \quad \sum_1^\infty [I(u_{(\theta,k)})](\cdot, l\Delta t_k) \rightarrow 0,$$

weakly, when  $k \rightarrow \infty$ .

Since

$$|I(u_{(\theta,k)}(x, 0)) - I(u_0(x))| = \left| \int_{u_0(x)}^{u_{(\theta,k)}(x,0)} h(\xi) d\xi \right| \leq H |u_{(\theta,k)}(x, 0) - u_0(x)|,$$

and

$$\begin{aligned}
|[I(u_{(\theta,k)})](\cdot, l\Delta t_k)| &= |I(u_{(\theta,k)}(x, l\Delta t_k^+) - I(u_{(\theta,k)}(x, l\Delta t_k^-))| \\
&\leq \left| \int_{u_{(\theta,k)}(x, l\Delta t_k^-)}^{u_{(\theta,k)}(x, l\Delta t_k^+)} h(\xi) d\xi \right| \\
&\leq H |u_{(\theta,k)}(x, l\Delta t_k^+) - u_{(\theta,k)}(x, l\Delta t_k^-)| \\
&\leq H |[u_{(\theta,k)}](\cdot, l\Delta t_k)|,
\end{aligned}$$

so the proof of the Lemma 5 is consequence of the next Lemma.

**Lemma 6.** *Let  $\theta \in \Phi$ . Then*

$$(20) \quad u_{(\theta,k)}(\cdot, 0) \rightarrow u_0(\cdot)$$

and

$$(21) \quad \sum_{l=1}^{\infty} [u_{(\theta,k)}](\cdot, l\Delta t_k) \rightarrow 0,$$

weakly, when  $k \rightarrow \infty$ .

Since  $u_{(\theta,k)}(x, 0) \rightarrow u_0(x)$ , when  $k \rightarrow \infty$ , and  $|u_{(\theta,k)}(x, 0)|, |u_0(x)| \leq M$ ,  $\forall x \in \mathbb{R}$ , we can obtain (20) using the Lebesgue Theorem.

Thus, we need to show that (21) holds. To this end, in [S], we have that

**Theorem 3.** *There is a null set  $N \subset \Phi$  and a subsequence  $\Delta x_{k_j} \rightarrow 0$  (consequently  $\Delta t_{k_j} \rightarrow 0$ ) such that for any  $\theta \in \Phi/N$  and any nonnegative function  $\phi \in C_0^1(t \geq 0)$ , (21) holds.*

The next theorem is our main result.

**Theorem 4.** *If  $u_0(\cdot)$  is bounded, continuous on the left and of locally bounded variation on  $\mathbb{R}$ , there exists a null set  $N \subset \Phi$  and a subsequence  $\Delta x_{k_j} \rightarrow 0$  such that if  $\theta \in \Phi/N$ ,  $h(u)$  is any nondecreasing function and  $\phi \in C_0^1(t \geq 0)$  is any nonnegative function, then  $u_\theta = \lim_{k_j \rightarrow \infty} u_{(\theta, k_j)}$  is such that  $\mathcal{L}_\phi(I(u_\theta), F(u_\theta)) \geq 0$ . Moreover,  $u_\theta$  satisfies the finite domain of dependence property.*

*Proof.* Assume first that  $u_0(\cdot)$  is of bounded variation, so choose a subsequence  $(\Delta x_{k_j})$  of  $(\Delta x_k)$  such that (20) holds. By Theorem 3, choose a subsequence of  $(\Delta x_{k_j})$ , for simplicity we write  $(\Delta x_{k_j})$ , such that for  $\theta \in \Phi/N$  (21) holds. By Theorem 2, choose a subsequence  $(u_{(\theta, k'_j)}) \subset (u_{(\theta, k_j)})$  such that  $(u_{(\theta, k'_j)})$  converges. Then by Lemma 4  $u_\theta$  is an admissible weak solution of (1).

For each  $j \in \mathbb{N}$ ,  $u_{(\theta, k'_j)}$  has the finite domain of dependence property, according to Remark 5, so  $u_\theta$  has the same property. Therefore, we can relax the assumption that  $u_0(\cdot)$  is of bounded variation on  $\mathbb{R}$  and replace it by the condition

that  $u_0(\cdot)$  is of locally bounded variation on  $\mathbb{R}$ . Furthermore,

$$TV_{[x_1, x_2]}(u_\theta(\cdot, t)) \leq TV_{[x_1 - (1+Kt), x_2 + (1+Kt)]}(u_0(\cdot)).$$

□

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