

On Pairs of Positive Solutions for a Class of Quasilinear Elliptic Problems *

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Abstract

We prove, by using bifurcation theory, the existence of at least two positive solutions for the quasilinear problem $-\Delta_p u = f(x, u)$ in Ω , $u = 0$ on $\partial\Omega$, where $p \geq 2$ and Ω is a smooth bounded domain in \mathbb{R}^N , $N \geq 2$ and the nonlinearity f is a locally Lipschitz continuous function among others assumptions.

1 Introduction

This paper is concerned with the existence and multiplicity of positive solutions for the problem

$$\begin{cases} -\Delta_p u = f(x, u), & \text{in } \Omega, \\ u = 0, & \text{on } \partial\Omega, \end{cases} \quad (1)$$

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where $\Delta_p u = \operatorname{div}(|\nabla u|^{p-2} \nabla u)$, $p \geq 2$ is the well known p -Laplacian operator. We will assume throughout the paper that Ω is a bounded smooth domain of \mathbb{R}^N , $N \geq 2$ and $f : \overline{\Omega} \times \mathbb{R}^+ \rightarrow \mathbb{R}$ is a locally Lipschitz continuous function and satisfies the following basic assumptions:

(f₁) $f(x, t) > 0$ for all $(x, t) \in \overline{\Omega} \times (0, +\infty)$;

(f₂) $f(x, 0) > 0$ or if $f(x, 0) = 0$ then $0 < a_0(x) := \lim_{t \rightarrow 0^+} \frac{f(x, t)}{t^{p-1}}$, uniformly in $\overline{\Omega}$, and $a_0 \in C^\alpha(\overline{\Omega})$ for some $\alpha \in (0, 1)$;

(f₃) there exists a function $a_\infty \in C^\alpha(\overline{\Omega})$, for some $\alpha \in (0, 1)$, such that $\lim_{t \rightarrow \infty} \frac{f(x, t)}{t^{p-1}} = a_\infty(x) > 0$, uniformly in $\overline{\Omega}$.

Let us denote by $\lambda_i(m)$, $i = 1, 2, \dots$, the eigenvalues of the Dirichlet eigenvalue problem

$$\begin{cases} -\Delta_p u = \lambda m(x) |u|^{p-2} u, & \text{in } \Omega, \\ u = 0, & \text{on } \partial\Omega, \end{cases} \quad (2)$$

where $m \in C^\alpha(\overline{\Omega})$ and $m(x) > 0$ in Ω . It is well known, cf. P. Drábek [8], that the first eigenvalue $\lambda_1(m) > 0$ is simple and its associated eigenfunction $\varphi_1 \in W_0^{1,p}(\Omega)$ may be taken positive in Ω and it is the unique eigenfunction with this property. Actually, $\varphi_1 \in C^{1,\alpha}(\overline{\Omega})$ (see P. Tolksdorf [15]).

Hereafter we assume the following:

$$\lambda_1(a_0) < 1 \quad \text{and} \quad \lambda_1(a_\infty) < 1. \quad (3)$$

From now on, we also suppose that Ω lies between two parallel planes a distance d apart and we put $C = e^d - 1$.

Theorem 1.1 *In addition to conditions (f₁) – (f₃) and (3), suppose that f satisfies the following condition*

(f₄) *there exist $m, t_0 > 0$ such that $C(f(x, t_0) + mt_0^{p-1}) < t_0$ for all $x \in \overline{\Omega}$ and $f(x, t) + mt^{p-1} \leq f(x, t_0) + mt_0^{p-1}$ for all $(x, t) \in \overline{\Omega} \times [0, t_0]$ with $p \geq 2$.*

Then problem (1) has at least two positive solutions u_1 and u_2 satisfying

$$0 < \|u_1\|_\infty < t_0 < \|u_2\|_\infty.$$

Remark 1.1 The existence of a positive solution for the problem has been studied by many authors. More recently, cf. De Paiva [13] considered the case where $\lambda_1(a_0) < 1 < \lambda_1(a_\infty)$, with λ_1 denoting the first eigenvalue of the weighted nonlinear problem (2) and $m(x)$ being a function in L^r space, $r > \frac{N}{p}$ if $1 < p \leq N$ and $r = 1$ if $p > N$, which can change sign in Ω . For problems using inequalities of type (3), see De Figueiredo & Lions [7], where the authors studied the semilinear case $p = 2$, and De Coster [6], for the one-dimensional case.

Remark 1.2 In [12], a-priori estimates for positive solutions of the problem

$$\begin{cases} -\Delta_p u = f(u), & \text{in } \Omega, \\ u = 0, & \text{on } \partial\Omega, \end{cases} \quad (4)$$

are obtained if $1 < p < 2$, f satisfies the conditions (f_5) , (f_6) , (f_7) and (f_8) below and the domain is strictly convex. Here, we may show a multiplicity result slightly similar to Theorem 2 in [2] for a class of sub-superlinear elliptic problems, by using a-priori bounds for positive solutions of problem (4) with $p \geq 2$ (see Proposition 2.2 below), and supposing in addition to this that $f : [0, +\infty) \rightarrow \mathbb{R}$ is strictly positive in $(0, +\infty)$ satisfying the assumptions (f_1) , (f_2) , (f_4) , and $(f_5) - (f_8)$ below.

Before enunciating our next result we establish some conditions on f . We will suppose that $f : [0, +\infty) \rightarrow \mathbb{R}$ is strictly positive and continuous in $(0, +\infty)$ satisfying:

$$(f_5) \quad f(t) \geq c_1 t^q \text{ for all } t \geq 0 \text{ for } c_1 > 0 \text{ and } q > p - 1;$$

$$(f_6) \quad \exists k > 0 \text{ such that } f(t) \leq c_2 t^{p-1} \text{ for } 0 \leq t \leq k \text{ where } c_2 > 0,$$

$$(f_7) \quad \lim_{t \rightarrow \infty} \frac{f(t)}{t^{p^*-1}} = 0 \text{ where } p^* = \frac{pN}{N-p} \text{ and } p < N;$$

$$(f_8) \quad \limsup_{t \rightarrow \infty} \frac{tf(t) - \tau F(t)}{t^{\frac{p(N-p+1)}{N}} f(t)^{\frac{p}{N}}} \leq 0 \text{ for some } 0 \leq \tau < p^*.$$

Now we may establish the following theorem, which is only stated for functions $f(x, r) = f(r)$.

Theorem 1.2 *Suppose that $f : [0, +\infty) \rightarrow \mathbb{R}$ is a strictly positive in the interval $(0, +\infty)$ and a C^1 function satisfying $(f_1), (f_2), (f_4)$ and $\lambda_1(a_0) < 1$. If, in addition, f satisfies $(f_5), (f_6), (f_7)$ and (f_8) with Ω strictly convex and $p \geq 2$, then problem (4) has at least two positive solutions u_1 and u_2 satisfying*

$$0 < \|u_1\|_\infty < t_0 < \|u_2\|_\infty.$$

2 Proofs.

Proof of Theorem 1.1. Consider the one parameter family of problems, namely

$$\begin{cases} -\Delta_p u = \lambda f(x, u), & \text{in } \Omega, \\ u = 0, & \text{on } \partial\Omega, \\ \lambda \geq 0. \end{cases} \quad (5)$$

Observe that for $\lambda = 1$, we have problem (1).

Using results on bifurcation theory (see [14]) we construct a component $\Sigma \subset \mathbb{R}^+ \times C^0(\bar{\Omega})$ of positive solutions of (5) which will be suitably conducted in order to meet the fiber $\{1\} \times C^0(\bar{\Omega}) \subset \mathbb{R}^+ \times C^0(\bar{\Omega})$ two times and so we produce two positive solutions for (1). More precisely, we proceed as follows. First we consider the auxiliary nonlinear eigenvalue problem

$$\begin{cases} -\Delta_p u = \lambda \tilde{f}(x, u), & \text{in } \Omega, \\ u = 0, & \text{on } \partial\Omega, \\ \lambda \geq 0, \end{cases} \quad (6)$$

where $\tilde{f} : \bar{\Omega} \times \mathbb{R} \rightarrow \mathbb{R}$ is the extension of f given by

$$\tilde{f}(x, t) = \begin{cases} f(x, 0) & \text{if } t \leq 0 \\ f(x, t) & \text{if } t > 0. \end{cases}$$

Let F be the Nemytskii operator $F : W_0^{1,p}(\Omega) \rightarrow W^{-1,p'}(\Omega)$ associated to \tilde{f} , that is, $F(u)(x) = \tilde{f}(x, u(x))$ for all $u \in W_0^{1,p}(\Omega)$, where $p' = \frac{p}{p-1}$. We may see, via elliptic regularity, that problem (6) is equivalent to the functional equation

$$u = \lambda LF(u), \quad u \in W_0^{1,p}(\Omega) \text{ and } \lambda \geq 0, \quad (7)$$

where $L := (-\Delta_p)^{-1} : W^{-1,p'}(\Omega) \rightarrow W_0^{1,p}(\Omega)$. Using the maximum principle [16], we have that if (λ, u) is a solution of (6) with $\lambda > 0$ then $u > 0$ in Ω

and so (λ, u) satisfies (5). Since $F : C^0(\overline{\Omega}) \cap W_0^{1,p}(\Omega) \subset W_0^{1,p}(\Omega) \rightarrow C^0(\overline{\Omega}) \cap W_0^{1,p}(\Omega) \subset W^{-1,p'}(\Omega)$ is continuous and $L = (-\Delta_p)^{-1} : C^0(\overline{\Omega}) \cap W_0^{1,p}(\Omega) \subset W^{-1,p'}(\Omega) \rightarrow C^0(\overline{\Omega}) \cap W_0^{1,p}(\Omega) \subset W_0^{1,p}(\Omega) \hookrightarrow L^q$, $q \in (1, p^*)$ is compact, $LF : C^0(\overline{\Omega}) \cap W_0^{1,p}(\Omega) \rightarrow C^0(\overline{\Omega}) \cap W_0^{1,p}(\Omega)$ is compact.

We now distinguish between two cases.

Case 1. $f(x, 0) > 0$. For this case, Rabinowitz theorem [14] implies that there is an unbounded component Σ of positive solutions of (5) meeting $(0, 0) \in \mathbb{R}^+ \times C^0(\overline{\Omega})$. In view of conditions $(f_1) - (f_3)$, there is a $\beta > 0$ so that $f(x, t) \geq \beta t^{p-1}$ for all $(x, t) \in \overline{\Omega} \times \mathbb{R}^+ \rightarrow \mathbb{R}^+$. By Picone's identity [1] and (5) we obtain

$$\lambda_1 \int_{\Omega} \varphi_1^p \geq \int_{\Omega} \frac{-\Delta_p u \varphi_1^p}{u^{p-1}} = \int_{\Omega} \frac{\lambda f(x, u) \varphi_1^p}{u^{p-1}} \geq \lambda \int_{\Omega} \frac{\beta u^{p-1}}{u^{p-1}} \varphi_1^p = \lambda \beta \int_{\Omega} \varphi_1^p$$

and so $\lambda \leq \frac{\lambda_1}{\beta}$. Consequently, the component Σ must be unbounded in u . So there is a sequence $(\lambda_n, u_n) \subset \Sigma$ in the strip $[0, \frac{\lambda_1}{\beta}] \times C^0(\overline{\Omega})$ such that $\lambda_n \rightarrow \lambda_0$ and $\|u_n\|_{\infty} \rightarrow \infty$. Thus

$$\begin{cases} -\Delta_p u_n = \lambda_n f(x, u_n), & \text{in } \Omega, \\ u_n = 0, & \text{on } \partial\Omega. \end{cases}$$

Setting $v_n = \frac{u_n}{\|u_n\|_{\infty}}$ we have

$$-\Delta_p v_n = \lambda_n \frac{f(x, u_n)}{\|u_n\|_{\infty}^{p-1}} \text{ in } \Omega, \quad v_n = 0, \text{ on } \partial\Omega. \quad (8)$$

Since f satisfies (f_2) and (f_3) , there is a constant $C > 0$ depending only on Ω and on the behavior of f in the limits arising in (f_2) and (f_3) such that $\|v_n\|_{W^{1,p}} \leq C$. In fact, multiplying both sides of equation (8) by v_n and integrating once we obtain

$$\|v_n\|_{W_0^{1,p}}^p = \int_{\Omega} |\nabla v_n|^p dx \leq \lambda_n \sup_{x \in \overline{\Omega}} \frac{f(x, u_n(x))}{\|u_n\|_{\infty}^{p-1}} \|v_n\|_{\infty} |\Omega| \leq C \quad \forall n.$$

From which, it follows that $v_n \rightharpoonup v_0$ in $W_0^{1,p}(\Omega)$, $v_n \rightarrow v_0$ in $L^q(\Omega)$, $q \in (1, p^*)$ and $v_n(x) \rightarrow v_0(x)$ a.e. in Ω . Hence, from the Dominated Convergence Theorem we have

$$\int_{\Omega} |\nabla v_0|^{p-2} \nabla v_0 \nabla \varphi = \int_{\Omega} \lambda_0 a_{\infty}(x) v_0^{p-1} \varphi,$$

$\forall \varphi \in W_0^{1,p}(\Omega)$. Because $v_0 \geq 0$, it follows, by the maximum principle [16], that $v_0 > 0$ in Ω and $\frac{\partial v_0}{\partial \eta} < 0$ on $\partial\Omega$. Then $\lambda_0 = \lambda_1(a_\infty)$ which implies that $(\lambda_1(a_\infty), \infty)$ is the only bifurcation point at infinity for positive solutions of (5). Note that we can not conclude, up to now, that Σ crosses $\lambda = 1$ because $\lambda_1(a_\infty) < 1$. For this we need the following result for quasilinear equations whose proof is similar to that found in [11], page 35.

Proposition 2.1 *If Ω lies between two parallel planes a distance d apart and $u \in C^{1,\alpha}(\bar{\Omega})$ satisfies*

$$-\Delta_p u + a|u|^{p-2}u = g(x) \in C(\bar{\Omega}) \text{ in } \Omega, u = 0 \text{ on } \partial\Omega,$$

where $a \geq 0$ is a constant, then

$$\|u\|_\infty \leq (e^d - 1)\|g\|_\infty. \quad (9)$$

Sketch of proof of Proposition 2.1. Let Ω lies in the slab $0 < x_1 < d$ and set $L_0 := \Delta_p$. We have

$$L_0 e^{x_1} = (p-1)e^{(p-1)x_1} \geq 1 \text{ for } p \geq 2.$$

Let

$$v = \sup_{\partial\Omega} u^+ + (e^d - e^{x_1}) \sup_{\Omega} |(-g)^-|.$$

Then, since

$$L_p v := L_0(v) - a|v|^{p-2}v \leq -(p-1) \sup_{\Omega} |(-g)^-|,$$

$$L_p v - L_p u \leq -((p-1) \sup_{\Omega} |(-g)^-| - g(x)) \leq 0$$

in Ω , and $v - u \geq 0$ on $\partial\Omega$. Hence, for $C = e^d - 1$, we obtain the desired result from the strong comparison principle [3]. \blacksquare

We claim that Σ meets $\lambda = 1$. Suppose by contradiction, that there is $(\lambda_0, u_0) \in \Sigma$ with $0 < \lambda_0 \leq 1$ and $\|u_0\|_\infty = t_0$. Thus,

$$-\Delta_p u_0 = \lambda_0 f(x, u_0) \text{ in } \Omega, u_0 = 0 \text{ on } \partial\Omega. \quad (10)$$

Let v_0 be the unique solution of

$$\begin{cases} -\Delta_p v_0 + m|v_0|^{p-2}v_0 = f(x, u_0) + m|u_0|^{p-2}u_0, & \text{in } \Omega, \\ v_0 = 0, & \text{on } \partial\Omega, \end{cases} \quad (11)$$

(see [10]). Applying the strong comparison principle (see Theorem 1 in [3]) for the weak solutions u_0 and v_0 of the partial differential equations (10) and (11), respectively, and using that $0 < \lambda_0 \leq 1$, it follows that $v_0 \geq u_0$ and so $t_0 = \|u_0\|_\infty \leq \|v_0\|_\infty$. By Proposition 2.1, we have

$$\|v_0\|_\infty \leq (e^d - 1)\|f(x, u_0(x)) + mu_0^{p-1}(x)\|_\infty.$$

Using (f_4) , we obtain

$$0 \leq f(x, u_0) + mu_0^{p-1} \leq f(x, t_0) + mt_0^{p-1},$$

and so

$$t_0 = \|u_0\|_\infty \leq \|v_0\|_\infty \leq (e^d - 1)f(x, t_0) + mt_0^{p-1} < t_0,$$

which is a contradiction. Hence, there is no $(\lambda, u) \in \Sigma$ with $0 \leq \lambda \leq 1$ and $\|u\|_\infty = t_0$. Since $(0, 0) \in \Sigma$ and Σ is a continuum of positive solutions, then crosses $\{1\} \times C^0(\bar{\Omega})$ below t_0 . This crossing produces the first solution u_1 of (1) with $0 < \|u_1\|_\infty < t_0$. The assumption $\lambda_1(a_\infty) < 1$ implies that Σ must bend back on itself and a second crossing of Σ with $\{1\} \times C^0(\bar{\Omega})$ is produced, generating a second solution u_2 above t_0 , that is, $\|u_2\|_\infty > t_0$.

Case 2. $f(x, 0) = 0$ and $\lambda(a_0) < 1$. In this case (see P. Drábek, A. Elkhailil & A. Touzani [9]), there exists an unbounded component Σ of positive solutions of $(1)_\lambda$ bifurcating from $(\lambda_1(a_0), 0)$, this being its unique bifurcation point for positive solutions in the line of trivial solutions. ■

Before proving Theorem 1.2, we present the following result on a-priori estimates for positive solutions of problem (4).

Proposition 2.2 *Let $u \in C^{1,\alpha}(\bar{\Omega})$ be a positive solution of (4). Assume Ω is strictly convex, $1 < p < \infty$ and $f : [0, +\infty) \rightarrow \mathbb{R}$ is strictly positive and locally Lipschitz continuous function in $(0, +\infty)$ satisfying the assumptions (f_1) , (f_2) , (f_4) , (f_5) – (f_8) . Then $\|u\|_{C^0(\bar{\Omega})}$ is a-priori bounded, that is, there is a constant C_∞ depending only on Ω and on the behavior of f such that $\|u\|_{C^0(\bar{\Omega})} \leq C_\infty$.*

Notice that for $1 < p < 2$, the Proposition 2.2 is Theorem 2.1 in [12]. The restriction on p appears, in Theorem 2.1, because the main tool used by the authors in the proof is the moving plane method applied to their problem with $1 < p < 2$ as in L. Damascelli & F. Pacella [4]. The Proposition 2.2 follows exactly as in Theorem 2.1 but here using a recent result proved by L.

Damascelli & B. Sciunzi [5], where they apply the moving plane method to a problem involving the p -Laplace operator with $p \geq 2$.

Proof of Theorem 1.2. The key to the proof is the construction of an truncation of f in order that we may use Theorem 1.1. In view of condition (f_5) , there exists $K > \lambda_1$ and $t_\infty > 0$ such that $f(t) > Kt^{p-1}$ if $t \geq t_\infty$. We now choose C_∞ as in Proposition 2.2 so that $C_\infty > \max\{t_0, t_\infty\}$. Let $h : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ be a function defined as follows:

If $0 \leq t \leq C_\infty$, define h by $h(t) = f(t) - Kt^{p-1}$. For $t \geq C_\infty$ we proceed in the following way. Note that there exists a straight line \tilde{h} through $(C_\infty, h(C_\infty))$, with negative slope, such that $\tilde{h}(t) \leq f(t) - Kt^{p-1}$ if $t \geq C_\infty$ because f is C^1 . Thus, there exists $C_1 > C_\infty$ so that $\tilde{h}(C_1) = 0$. Now we define $h(t) = \tilde{h}(t)$ if $C_\infty \leq t \leq C_1$ and $h(t) = 0$ if $t \geq C_1$. Thus h is bounded and locally Lipschitz continuous function.

Let $\tilde{f} : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ be a function given by $\tilde{f}(t) = Kt^{p-1} + h(t)$. In this case $a_\infty = K$ and so $\lambda_1(a_\infty) < 1$ because $K > \lambda_1$. From the Proposition 2.2 we have that if u is a positive solution of

$$-\Delta u = \tilde{f}(u) \text{ in } \Omega, \quad u = 0 \text{ on } \partial\Omega, \quad (12)$$

then $\|u\|_{C^0(\bar{\Omega})} \leq C_\infty$. In view of Theorem 1.1, problem (12) possesses two positive solutions u_1 and u_2 satisfying $0 < \|u_1\|_\infty < t_0 < \|u_2\|_\infty$. Furthermore, $0 < u_1(x), u_2(x) \leq C_\infty$ and, because $f(t) = \tilde{f}(t)$ for all $t \in [0, C_\infty]$, we have that u_1 and u_2 are solutions of (3). ■

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